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FAST TRACK COMMUNICATION

Soliton resonances in a generalized nonlinear Schrödinger equation

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Abstract

It is shown that a generalized nonlinear Schrödinger equation proposed by Malomed and Stenflo admits, for a specific range of parameters, resonant soliton interaction. The equation is transformed to the 'resonant' nonlinear Schrödinger equation, as originally introduced to describe black holes in a Madelung fluid and recently derived in the context of uniaxial wave propagation in a cold collisionless plasma. A Hirota bilinear representation is obtained and soliton solutions are thereby derived. The one-soliton solution interpretation in terms of a black hole in two-dimensional spacetime is given. For the twosoliton solution, resonant interactions of several kinds are found. The addition of a quantum potential term is considered and the reduction is obtained to the resonant NLS equation.

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(Some figures in this article are in colour only in the electronic version)

1. Malomed-Stenflo NLS and RNLS connections

In a search for generalizations of the nonlinear Schrödinger equation which admit Hamiltonian form, Malomed and Stenflo [1] derived the equation

$$iu_t + u_{xx} + 2p|u|^2 u = \left(\bar{c}\frac{u_x^2}{u^2} + c\frac{\bar{u}_x^2}{\bar{u}^2} - 2c\frac{\bar{u}_{xx}}{\bar{u}} - 2c\frac{\bar{u}_x u_x}{\bar{u}u}\right)u$$
(1)

with the Hamiltonian density

$$\mathcal{H} = |u_x|^2 - p|u|^4 + c\frac{u}{\bar{u}}\bar{u}_x^2 + \bar{c}\frac{\bar{u}}{u}u_x^2$$
(2)

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and the complex parameter $c = c_1 + ic_2$. As was shown by Natterman [2], under the restriction of this parameter to the open disc $|c| < \frac{1}{2}$, equation (1) can be transformed into the NLS equation and, accordingly, is integrable (see also Auberson and Sabatier [3] for real c). Here, it will be shown that (1) is integrable for all values of the complex parameter c, and that, in a specific range of the parameters, it admits resonance solitons.

If we set $u = e^{R+iS}$ then (1) yields

$$-S_t - (1 - 2c_1)S_x^2 + 2p e^{2R} + 2c_2S_{xx} + (1 + 2c_1)(R_{xx} + R_x^2) = 0,$$
(3)

$$R_t + (1 - 2c_1)(S_{xx} + 2R_x S_x) + 2c_2 R_{xx} + 4c_2 R_x^2 = 0$$
(4)

and it is readily seen that the linear transformation

$$S = \hat{S} + \frac{2c_2}{2c_1 - 1}\hat{R}, \qquad R = \hat{R}, \qquad \hat{t} = (2c_1 - 1)t \tag{5}$$

transforms this system into the Madelung form

$$\hat{S}_{\hat{i}} - \hat{S}_{x}^{2} - \frac{2p}{2c_{1} - 1} e^{2\hat{R}} - \frac{4|c|^{2} - 1}{(2c_{1} - 1)^{2}} (\hat{R}_{xx} + \hat{R}_{x}^{2}) = 0$$
(6)

$$-\hat{R}_{\hat{i}} + (\hat{S}_{xx} + 2\hat{R}_x\hat{S}_x) = 0.$$
⁽⁷⁾

Introduction of the new wavefunction

$$\psi = e^{\hat{R} - i\hat{S}} \tag{8}$$

produces the resonant NLS (RNLS) equation of Pashaev and Lee [4],

$$i\psi_{\hat{t}} + \psi_{xx} - \frac{2p}{2c_1 - 1}|\psi|^2\psi = s\frac{|\psi|_{xx}}{|\psi|}\psi,$$
(9)

where

$$s = 1 + \frac{4|c|^2 - 1}{(2c_1 - 1)^2}.$$
(10)

2. RNLS reductions

2.1. Undercritical case

If s < 1 so that $|c| < \frac{1}{2}$, then on rescaling time and the phase of the wavefunction according to

$$\hat{t} = \frac{t}{\sqrt{1-s}}, \qquad \hat{S}(x,t) = \sqrt{1-s}\tilde{S}(x,\tilde{t}), \qquad \hat{R}(x,t) = \tilde{R}(x,\tilde{t}), \tag{11}$$

where

$$\sqrt{1-s} = \frac{1-4|c|^2}{(1-2c_1)^2},\tag{12}$$

then we retrieve the usual NLS equation

$$i\tilde{\psi}_{\tilde{t}} + \tilde{\psi}_{xx} + 2p \frac{1 - 2c_1}{1 - 4|c|^2} |\tilde{\psi}|^2 \tilde{\psi} = 0$$
(13)

in $\tilde{\psi} = e^{\tilde{R} - i\tilde{S}}$. This, as in [2], establishes that when $|c| < \frac{1}{2}$ the Malomed–Steflo equation (1) may be transformed into the standard NLS equation.

2.2. Critical case

If s = 1 so that $|c| = \frac{1}{2}$, then on the circle $c_1^2 + c_2^2 = \frac{1}{4}$ equation (9) becomes dispersionless and the resultant NLS equation can be linearized.

2.3. Special case

In the special case when $c_1 = \frac{1}{2}$ and c_2 is an arbitrary real number, the system (3)–(4) reduces [2] to the heat equation

$$-S_t + 2c_2 S_{xx} + 2p\rho + 2\frac{(\sqrt{\rho})_{xx}}{\sqrt{\rho}} = 0$$
(14)

with density and quantum potential-type sources, together with the heat equation

$$\rho_t + 2c_2 \rho_{xx} = 0. (15)$$

for the density $\rho = |u|^2 = e^{2R}$.

2.4. Overcritical (resonant) case

If s > 1, so that $|c| > \frac{1}{2}$ then except on the vertical line $c = \frac{1}{2} + ic_2$, the RNLS equation cannot be reduced to the NLS form. However, the rescaling

$$\hat{t} = \frac{\tilde{t}}{\sqrt{s-1}}, \qquad \hat{S}(x,t) = \sqrt{s-1}\tilde{S}(x,\tilde{t}), \qquad \hat{R}(x,t) = \tilde{R}(x,\tilde{t}), \tag{16}$$

where

$$\sqrt{s-1} = \frac{\sqrt{4|c|^2 - 1}}{|2c_1 - 1|} \tag{17}$$

and the introduction of the two real functions E^+ , E^- according to

$$E^{+} = e^{\tilde{R} + \tilde{S}}, \qquad E^{-} = -e^{\tilde{R} - \tilde{S}}$$
(18)

produces the coupled system

$$-E_{\tilde{i}}^{+} + E_{xx}^{+} + 2p \frac{2c_1 - 1}{4|c|^2 - 1} E^+ E^- E^+ = 0,$$
(19)

$$E_{\tilde{i}}^{-} + E_{xx}^{-} + 2p \frac{2c_1 - 1}{4|c|^2 - 1} E^+ E^- E^- = 0.$$
⁽²⁰⁾

2.5. Bilinear representation of the resonant case

The system (19) and (20) can be bilinearized in terms of three real functions G^+ , G^- and F where

$$E^{+} = \sqrt{\frac{4|c|^{2} - 1}{|p(2c_{1} - 1)|}} \frac{G^{+}}{F}, \qquad E^{-} = \sqrt{\frac{4|c|^{2} - 1}{|p(2c_{1} - 1)|}} \frac{G^{-}}{F}$$
(21)

satisfy the system

$$(+D_{\tilde{t}} - D_x^2)(G^+ \cdot F) = 0,$$
 (22)

$$(-D_{\tilde{t}} - D_x^2)(G^- \cdot F) = 0,$$
 (23)

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Figure 1. The complex *c* plane. The region inside the circle $|c| < \frac{1}{2}$ corresponds to the NLS. The circle $|c| = \frac{1}{2}$ is associated with the dispersionless limit of the NLS. Points along the vertical line $x = \frac{1}{2}$ correspond to linear diffusion reductions. The region $|c| > \frac{1}{2}$ corresponds to the resonant case. The right half-plane with $c_1 > \frac{1}{2}$ admits nonsingular solutions for the coupling constant p < 0, and for the left half-plane $c_1 < \frac{1}{2}$ for p > 0.

$$D_{x}^{2}(F \cdot F) = 2\kappa^{2}G^{+}G^{-}, \qquad (24)$$

where the latter equation shows that

$$-|u|^{2} = E^{+}E^{-} = \kappa^{2} \frac{4|c|^{2} - 1}{|p(2c_{1} - 1)|} (\ln F)_{xx}, \qquad (25)$$

where $\kappa^2 = \text{sign } p((2c_1 - 1)) = \pm 1$.

In the focusing case p > 0, for $c_1 > \frac{1}{2}$ we have $\kappa^2 = 1$ while for $c_1 < \frac{1}{2}$ we have $\kappa^2 = -1$ (see figure 1).

In the defocusing case p < 0, for $c_1 > \frac{1}{2}$ we have $\kappa^2 = -1$ while for $c_1 < \frac{1}{2}$ we have $\kappa^2 = +1$ (see figure 1).

It is noted that the solution u of the Malomed–Stenflo equation (1) may be written explicitly in a bilinear form as

$$u(x,t) = \left[\frac{4|c|^2 - 1}{|p(2c_1 - 1)|} \frac{1}{F^2} \left(\frac{G^+}{-G^-}\right)^{i\frac{\sqrt{4|c|^2 - 1}}{2|2c_1 - 1|}}\right]^{\frac{2d^2 - 1}{2(2c_1 - 1)}},$$
(26)

2 - 1

where $G^{\pm}(x,\tilde{t}) = G^{\pm}(x,\sqrt{4|c|^2 - 1t}), F(x,\tilde{t}) = F(x,\sqrt{4|c|^2 - 1t}), c = c_1 + ic_2.$

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2.6. Single-soliton solution

For the one-soliton solution we have

$$G^{\pm} = \pm e^{\eta_1^{\pm}}, \qquad F = 1 - \kappa^2 e^{\eta_1^{+} + \eta_1^{-} + \phi_{11}}, \qquad e^{\phi_{11}} = \frac{1}{\left(k_1^{+} + k_1^{-}\right)^2}, \tag{27}$$

where $\eta_1^{\pm} = k_1^{\pm} x \pm (k_1^{\pm})^2 \tilde{t} + \eta_1^{\pm(0)}$, and $k_1^{\pm}, \eta_1^{\pm(0)}$ are arbitrary real constants. This solution is regular only if $\kappa^2 < 0$, which corresponds to the cases p > 0, $c_1 < \frac{1}{2}$ or p < 0, $c_1 > \frac{1}{2}$, when $\kappa^2 = -1$ (see figure 1). Here, we focus on this case. From the preceding we have

$$e^{\hat{R}} = \sqrt{\frac{4|c|^2 - 1}{|p(2c_1 - 1)|} \frac{\left|k_1^+ + k_1^-\right|}{2\cosh\frac{\eta_1^+ + \eta_1^- + \phi_{11}}{2}}}, \qquad \hat{S} = \frac{\sqrt{4|c|^2 - 1}}{|2c_1 - 1|} \frac{\eta_1^+ - \eta_1^-}{2}.$$
(28)

Denoting $v \equiv (k_1^- - k_1^+)\sqrt{4|c|^2 - 1}$, $k \equiv (k_1^- + k_1^+)/2$ and using $\tilde{t} = \pm \sqrt{4|c|^2 - 1}t$ we obtain a single-soliton solution of the model (1) in the form

$$u(x,t) = \sqrt{\frac{4|c|^2 - 1}{|p(2c_1 - 1)|}} \frac{|k| e^{i\Phi(x,t)}}{\cosh k(x - vt - x_0)},$$
(29)

where

$$\Phi = \frac{1}{|2c_1 - 1|} \left[-\frac{vx}{2} + \left[(4|c|^2 - 1)k^2 + \frac{v^2}{4} \right] t \right] - \frac{2c_2}{2c_1 - 1} \ln[\cosh k(x - vt - x_0)] + \phi_0.$$
(30)

2.7. Hyperbolic metrics and black hole interpretation

Substitution of the Madelung form $u = e^{R+iS}$ into the Hamiltonian density (2) yields

$$\mathcal{H} = \left[(1+2c_1)R_x^2 + (1-2c_1)S_x^2 + 4c_2R_xS_x \right] e^{2R} - p e^{4R}.$$
(31)

The dispersion is positive definite if $|c| < \frac{1}{2}$ and indefinite when $|c| > \frac{1}{2}$. In the present resonant case, the dispersion is of indefinite sign. Thus in terms of (5)

$$\mathcal{H} = \left[\left(\frac{4|c|^2 - 1}{2c_1 - 1} \right) \hat{R}_x^2 + (1 - 2c_1) \hat{S}_x^2 \right] e^{2\hat{R}} - p e^{4\hat{R}}$$
(32)

whence, when $|c| > \frac{1}{2}$ the dispersion is indefinite and it changes sign at points in the spacetime where

$$\hat{R}_x = \pm \frac{1 - 2c_1}{\sqrt{4|c|^2 - 1}} \hat{S}_x.$$
(33)

For the one-soliton solution (29) this gives

$$\tanh k(x - vt - x_0) = \pm \frac{v}{2k},$$
(34)

a solution of which exists if |v| < 2|k|. As in [4, 5], we can construct a two-dimensional pseudo-Riemannian metric for (19), (20) and the RNLS, namely

$$dl^{2} = \left[(4|c|^{2} - 1)\hat{R}_{x}^{2} - (2c_{1} - 1)^{2}\hat{S}_{x}^{2} \right] e^{2\hat{R}} dt^{2} - 2\hat{S}_{x}|2c_{1} - 1| e^{2\hat{R}} dx dt - e^{2\hat{R}} dx^{2}$$
(35)

so that evolution according to equation (1) implies the two-dimensional spacetime with the constant scalar curvature

$$R = 8p \frac{2c_1 - 1}{4|c|^2 - 1}.$$
(36)

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Figure 2. Fusion and fission of two solitons (a) fusion of two solitons (b) fission of two solitons.

With our choice of parameters, namely $c_1 > \frac{1}{2}$, p < 0 or $c_1 < \frac{1}{2}$, p > 0, R is negative-valued. The time component of the metric is the dispersion term ϵ_0 for the energy

$$g_{00} = \left[(4|c|^2 - 1)\hat{R}_x^2 - (2c_1 - 1)^2 \hat{S}_x^2 \right] e^{2\hat{R}} = (2c_1 - 1)\epsilon_0.$$
(37)

Points where g_{00} vanishes correspond to the event horizon of a black hole. For the one-soliton solution this corresponds to condition (34). Solitons of the equation (1) moving with the velocity |v| < 2|k| correspond to black holes with event horizon dependent on the velocity of the soliton.

2.8. Two-soliton solution

The Hirota bilinear representation (22)-(24) admits two-soliton solutions with

$$G^{\pm} = \pm \left(e^{\eta_1^{\pm}} + e^{\eta_2^{\pm}} + \alpha_1^{\pm} e^{\eta_1^{+} + \eta_1^{-} + \eta_2^{\pm}} + \alpha_2^{\pm} e^{\eta_2^{+} + \eta_2^{-} + \eta_1^{\pm}} \right),$$
(38)

$$F = 1 + \frac{e^{\eta_1^+ + \eta_1^-}}{\left(k_{11}^{+-}\right)^2} + \frac{e^{\eta_1^+ + \eta_2^-}}{\left(k_{21}^{+-}\right)^2} + \frac{e^{\eta_2^+ + \eta_1^-}}{\left(k_{21}^{+-}\right)^2} + \frac{e^{\eta_2^+ + \eta_2^-}}{\left(k_{22}^{+-}\right)^2} + \beta e^{\eta_1^+ + \eta_1^- + \eta_2^+ + \eta_2^-},$$
(39)

where $\eta_i^{\pm} = k_i^{\pm} x \pm (k_i^{\pm})^2 \tilde{t} + \eta_i^{\pm(0)}, k_{ij}^{ab} = k_i^a + k_j^b, (i, j = 1, 2), (a, b = +-),$

$$\alpha_{1}^{\pm} = \frac{\left(k_{1}^{\pm} - k_{2}^{\pm}\right)^{2}}{\left(k_{11}^{+-}k_{21}^{\pm\mp}\right)^{2}}, \qquad \alpha_{2}^{\pm} = \frac{\left(k_{1}^{\pm} - k_{2}^{\pm}\right)^{2}}{\left(k_{22}^{+-}k_{12}^{\pm\mp}\right)^{2}}, \qquad \beta = \frac{\left(k_{1}^{+} - k_{2}^{+}\right)^{2}\left(k_{1}^{--} - k_{2}^{--}\right)^{2}}{\left(k_{11}^{+-}k_{21}^{+-}k_{21}^{+-}k_{22}^{+--}\right)^{2}}.$$
(40)

2.9. Resonance interaction of solitons

In figure 2, fusion and fission of two solitons is shown for the parameter values $k_1^+ = 0.1$, $k_1^- = 1$, $k_2^- = 1$, $k_2^- = 0$ and large phase shift. The horizontal and vertical axes represent space *x* and time *t* coordinates, respectively.



Figure 3. Two-soliton resonant state.



Figure 4. Four-soliton resonance scattering.

In figure 3, the creation of soliton resonance with a finite lifetime is shown. The parameters in this case are the same as above, except for the phase shift d = 15.

In figure 4, four virtual soliton resonance scattering is shown for $k_1^+ = 2$, $k_1^- = 1$, $k_2^+ = 1$, $k_2^- = 2$ and d = 16.

3. Nontrivial boundary conditions

In the application of the RNLS model to the propagation of solitonic magnetoacoustic waves in [6] the required asymptotic behavior is $|\psi|^2 = \rho \rightarrow 1$ at infinity. In this case, we can derive a one-soliton solution of (1) with

$$|u|^{2}(x,t) = 1 + \frac{v^{2} - 4p(1 - 2c_{1})}{4p(1 - 2c_{1})}\operatorname{sech}^{2}\left[\frac{\sqrt{v^{2} - 4p(1 - 2c_{1})}}{2\sqrt{4|c|^{2} - 1}}(x + vt + x_{0})\right]$$
(41)

and the phase

$$S(x,t) = S_0 + 2pt + \frac{c_2}{2c_1 - 1} \ln |u|^2(x,t)$$
(42)

$$+\frac{\sqrt{4|c|^{2}-1}}{2|2c_{1}-1|}\ln\frac{v+\sqrt{v^{2}-4p(1-2c_{1})}\tanh\left[\frac{\sqrt{v^{2}-4p(1-2c_{1})}}{2\sqrt{4|c|^{2}-1}}(x+vt+x_{0})\right]}{v-\sqrt{v^{2}-4p(1-2c_{1})}\tanh\left[\frac{\sqrt{v^{2}-4p(1-2c_{1})}}{2\sqrt{4|c|^{2}-1}}(x+vt+x_{0})\right]}.$$
(43)

It is seen that the velocity of this soliton is bounded below with $|v| > 2|p(1-2c_1)|$. This contrasts with the case of the defocusing NLS equation where the dark soliton velocity is bounded above. Moreover if the soliton of the defocusing NLS is a hole-like (bubble) excitation with $\rho = |u|^2 < 1$, for the Malomed–Stenflo equation this has $\rho = |u|^2 > 1$. It is noted that the two-soliton solution can be constructed alternatively via a Backlund–Darboux transformation [6]. Solutions of the RNLS equation with nontrivial boundary conditions have been investigated by Lee and Pashaev in [7]. These results may be carried over '*mutatis mutandis*' to the Malomed–Stenflo equation (1).

4. Conclusion

It has been established that the generalized nonlinear Schrödinger equation (1) introduced in [1], for a specific range of parameters, admits resonant soliton interaction. Indeed, a natural integrable extension of this equation is suggested, namely

$$iu_t + u_{xx} + 2p|u|^2 u = \left(\bar{c}\frac{u_x^2}{u^2} + c\frac{\bar{u}_x^2}{\bar{u}^2} - 2c\frac{\bar{u}_{xx}}{\bar{u}} - 2c\frac{\bar{u}_x u_x}{\bar{u}u}\right)u + 4\nu \frac{|u|_{xx}}{|u|}u$$
(44)

corresponding to the addition of a 'quantum potential' term with strength ν . This extension can be motivated in an information theory context to reflect uncertainty conditions in the measurement process and described by the Fisher measure [8]. The generalized NLS equation (44) is Hamiltonian with

$$\mathcal{H} = |u_x|^2 - p|u|^4 + c\frac{u}{\bar{u}}\bar{u}_x^2 + \bar{c}\frac{\bar{u}}{u}u_x^2 - 4\nu(|u|_x)^2.$$
(45)

Following the same procedure as that for (1), reduction may be made to the RNLS form (9) but now with the parameter

$$s = 1 + \frac{4|c|^2 - 1 - 4\nu(2c_1 - 1)}{(2c_1 - 1)^2}.$$
(46)

The reductions of the extended model equation (44) then depend on both the complex parameter $c = c_1 + ic_2$ and the real quantum potential strength ν . In geometrical terms, the circle $|c| = \frac{1}{2}$ in figure 1 is modified by the presence of the additional parameter ν to become

$$(c_1 - \nu)^2 + c_2^2 = \left(\nu - \frac{1}{2}\right)^2.$$
(47)

The region inside this circle corresponds to the NLS reduction, while the outside corresponds to the resonant NLS case. It is noted that when $\nu = \frac{1}{2}$, the disc shrinks to a point and no reduction to the classical NLS is possible. In this case

$$s = 1 + \frac{(2c_1 - 1)^2 + 4c_2^2}{(2c_1 - 1)^2}$$
(48)

whence s > 1 and the model equation (44) is necessarily of resonant type.

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