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## FAST TRACK COMMUNICATION

## Soliton resonances in a generalized nonlinear Schrödinger equation

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#### Abstract

It is shown that a generalized nonlinear Schrödinger equation proposed by Malomed and Stenflo admits, for a specific range of parameters, resonant soliton interaction. The equation is transformed to the 'resonant' nonlinear Schrödinger equation, as originally introduced to describe black holes in a Madelung fluid and recently derived in the context of uniaxial wave propagation in a cold collisionless plasma. A Hirota bilinear representation is obtained and soliton solutions are thereby derived. The one-soliton solution interpretation in terms of a black hole in two-dimensional spacetime is given. For the twosoliton solution, resonant interactions of several kinds are found. The addition of a quantum potential term is considered and the reduction is obtained to the resonant NLS equation.


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(Some figures in this article are in colour only in the electronic version)

## 1. Malomed-Stenflo NLS and RNLS connections

In a search for generalizations of the nonlinear Schrödinger equation which admit Hamiltonian form, Malomed and Stenflo [1] derived the equation

$$
\begin{equation*}
\mathrm{i} u_{t}+u_{x x}+2 p|u|^{2} u=\left(\bar{c} \frac{u_{x}^{2}}{u^{2}}+c \frac{\bar{u}_{x}^{2}}{\bar{u}^{2}}-2 c \frac{\bar{u}_{x x}}{\bar{u}}-2 c \frac{\bar{u}_{x} u_{x}}{\bar{u} u}\right) u \tag{1}
\end{equation*}
$$

with the Hamiltonian density

$$
\begin{equation*}
\mathcal{H}=\left|u_{x}\right|^{2}-p|u|^{4}+c \frac{u}{\bar{u}} \bar{u}_{x}^{2}+\bar{c} \frac{\bar{u}}{u} u_{x}^{2} \tag{2}
\end{equation*}
$$

and the complex parameter $c=c_{1}+\mathrm{i} c_{2}$. As was shown by Natterman [2], under the restriction of this parameter to the open disc $|c|<\frac{1}{2}$, equation (1) can be transformed into the NLS equation and, accordingly, is integrable (see also Auberson and Sabatier [3] for real c). Here, it will be shown that (1) is integrable for all values of the complex parameter $c$, and that, in a specific range of the parameters, it admits resonance solitons.

If we set $u=\mathrm{e}^{R+\mathrm{i} S}$ then (1) yields

$$
\begin{align*}
& -S_{t}-\left(1-2 c_{1}\right) S_{x}^{2}+2 p \mathrm{e}^{2 R}+2 c_{2} S_{x x}+\left(1+2 c_{1}\right)\left(R_{x x}+R_{x}^{2}\right)=0,  \tag{3}\\
& R_{t}+\left(1-2 c_{1}\right)\left(S_{x x}+2 R_{x} S_{x}\right)+2 c_{2} R_{x x}+4 c_{2} R_{x}^{2}=0 \tag{4}
\end{align*}
$$

and it is readily seen that the linear transformation

$$
\begin{equation*}
S=\hat{S}+\frac{2 c_{2}}{2 c_{1}-1} \hat{R}, \quad R=\hat{R}, \quad \hat{t}=\left(2 c_{1}-1\right) t \tag{5}
\end{equation*}
$$

transforms this system into the Madelung form

$$
\begin{align*}
& \hat{S}_{\hat{t}}-\hat{S}_{x}^{2}-\frac{2 p}{2 c_{1}-1} \mathrm{e}^{2 \hat{R}}-\frac{4|c|^{2}-1}{\left(2 c_{1}-1\right)^{2}}\left(\hat{R}_{x x}+\hat{R}_{x}^{2}\right)=0  \tag{6}\\
& -\hat{R}_{\hat{t}}+\left(\hat{S}_{x x}+2 \hat{R}_{x} \hat{S}_{x}\right)=0 \tag{7}
\end{align*}
$$

Introduction of the new wavefunction

$$
\begin{equation*}
\psi=\mathrm{e}^{\hat{R}-\mathrm{i} \hat{S}} \tag{8}
\end{equation*}
$$

produces the resonant NLS (RNLS) equation of Pashaev and Lee [4],

$$
\begin{equation*}
\mathrm{i} \psi_{\hat{t}}+\psi_{x x}-\frac{2 p}{2 c_{1}-1}|\psi|^{2} \psi=s \frac{|\psi|_{x x}}{|\psi|} \psi \tag{9}
\end{equation*}
$$

where

$$
\begin{equation*}
s=1+\frac{4|c|^{2}-1}{\left(2 c_{1}-1\right)^{2}} \tag{10}
\end{equation*}
$$

## 2. RNLS reductions

### 2.1. Undercritical case

If $s<1$ so that $|c|<\frac{1}{2}$, then on rescaling time and the phase of the wavefunction according to
$\hat{t}=\frac{\tilde{t}}{\sqrt{1-s}}, \quad \hat{S}(x, t)=\sqrt{1-s} \tilde{S}(x, \tilde{t}), \quad \hat{R}(x, t)=\tilde{R}(x, \tilde{t})$,
where

$$
\begin{equation*}
\sqrt{1-s}=\frac{1-4|c|^{2}}{\left(1-2 c_{1}\right)^{2}} \tag{12}
\end{equation*}
$$

then we retrieve the usual NLS equation

$$
\begin{equation*}
\mathrm{i} \tilde{\psi}_{\tilde{t}}+\tilde{\psi}_{x x}+2 p \frac{1-2 c_{1}}{1-4|c|^{2}}|\tilde{\psi}|^{2} \tilde{\psi}=0 \tag{13}
\end{equation*}
$$

in $\tilde{\psi}=\mathrm{e}^{\tilde{R}-\mathrm{i} \tilde{S}}$. This, as in [2], establishes that when $|c|<\frac{1}{2}$ the Malomed-Steflo equation (1) may be transformed into the standard NLS equation.

### 2.2. Critical case

If $s=1$ so that $|c|=\frac{1}{2}$, then on the circle $c_{1}^{2}+c_{2}^{2}=\frac{1}{4}$ equation (9) becomes dispersionless and the resultant NLS equation can be linearized.

### 2.3. Special case

In the special case when $c_{1}=\frac{1}{2}$ and $c_{2}$ is an arbitrary real number, the system (3)-(4) reduces [2] to the heat equation

$$
\begin{equation*}
-S_{t}+2 c_{2} S_{x x}+2 p \rho+2 \frac{(\sqrt{\rho})_{x x}}{\sqrt{\rho}}=0 \tag{14}
\end{equation*}
$$

with density and quantum potential-type sources, together with the heat equation

$$
\begin{equation*}
\rho_{t}+2 c_{2} \rho_{x x}=0 \tag{15}
\end{equation*}
$$

for the density $\rho=|u|^{2}=\mathrm{e}^{2 R}$.

### 2.4. Overcritical (resonant) case

If $s>1$, so that $|c|>\frac{1}{2}$ then except on the vertical line $c=\frac{1}{2}+\mathrm{i} c_{2}$, the RNLS equation cannot be reduced to the NLS form. However, the rescaling
$\hat{t}=\frac{\tilde{t}}{\sqrt{s-1}}, \quad \hat{S}(x, t)=\sqrt{s-1} \tilde{S}(x, \tilde{t}), \quad \hat{R}(x, t)=\tilde{R}(x, \tilde{t})$,
where

$$
\begin{equation*}
\sqrt{s-1}=\frac{\sqrt{4|c|^{2}-1}}{\left|2 c_{1}-1\right|} \tag{17}
\end{equation*}
$$

and the introduction of the two real functions $E^{+}, E^{-}$according to

$$
\begin{equation*}
E^{+}=\mathrm{e}^{\tilde{R}+\tilde{S}}, \quad E^{-}=-\mathrm{e}^{\tilde{R}-\tilde{S}} \tag{18}
\end{equation*}
$$

produces the coupled system

$$
\begin{align*}
& -E_{\tilde{t}}^{+}+E_{x x}^{+}+2 p \frac{2 c_{1}-1}{4|c|^{2}-1} E^{+} E^{-} E^{+}=0  \tag{19}\\
& E_{\tilde{t}}^{-}+E_{x x}^{-}+2 p \frac{2 c_{1}-1}{4|c|^{2}-1} E^{+} E^{-} E^{-}=0 \tag{20}
\end{align*}
$$

### 2.5. Bilinear representation of the resonant case

The system (19) and (20) can be bilinearized in terms of three real functions $G^{+}, G^{-}$and $F$ where

$$
\begin{equation*}
E^{+}=\sqrt{\frac{4|c|^{2}-1}{\left|p\left(2 c_{1}-1\right)\right|}} \frac{G^{+}}{F}, \quad E^{-}=\sqrt{\frac{4|c|^{2}-1}{\left|p\left(2 c_{1}-1\right)\right|}} \frac{G^{-}}{F} \tag{21}
\end{equation*}
$$

satisfy the system

$$
\begin{align*}
& \left(+D_{\tilde{t}}-D_{x}^{2}\right)\left(G^{+} \cdot F\right)=0  \tag{22}\\
& \left(-D_{\tilde{t}}-D_{x}^{2}\right)\left(G^{-} \cdot F\right)=0 \tag{23}
\end{align*}
$$



Figure 1. The complex $c$ plane. The region inside the circle $|c|<\frac{1}{2}$ corresponds to the NLS. The circle $|c|=\frac{1}{2}$ is associated with the dispersionless limit of the NLS. Points along the vertical line $x=\frac{1}{2}$ correspond to linear diffusion reductions. The region $|c|>\frac{1}{2}$ corresponds to the resonant case. The right half-plane with $c_{1}>\frac{1}{2}$ admits nonsingular solutions for the coupling constant $p<0$, and for the left half-plane $c_{1}<\frac{1}{2}$ for $p>0$.

$$
\begin{equation*}
D_{x}^{2}(F \cdot F)=2 \kappa^{2} G^{+} G^{-}, \tag{24}
\end{equation*}
$$

where the latter equation shows that

$$
\begin{equation*}
-|u|^{2}=E^{+} E^{-}=\kappa^{2} \frac{4|c|^{2}-1}{\left|p\left(2 c_{1}-1\right)\right|}(\ln F)_{x x}, \tag{25}
\end{equation*}
$$

where $\kappa^{2}=\operatorname{sign} p\left(\left(2 c_{1}-1\right)\right)= \pm 1$.
In the focusing case $p>0$, for $c_{1}>\frac{1}{2}$ we have $\kappa^{2}=1$ while for $c_{1}<\frac{1}{2}$ we have $\kappa^{2}=-1$ (see figure 1).

In the defocusing case $p<0$, for $c_{1}>\frac{1}{2}$ we have $\kappa^{2}=-1$ while for $c_{1}<\frac{1}{2}$ we have $\kappa^{2}=+1$ (see figure 1 ).

It is noted that the solution $u$ of the Malomed-Stenflo equation (1) may be written explicitly in a bilinear form as

$$
\begin{equation*}
u(x, t)=\left[\frac{4|c|^{2}-1}{\left|p\left(2 c_{1}-1\right)\right|} \frac{1}{F^{2}}\left(\frac{G^{+}}{-G^{-}}\right)^{\mathrm{i} \frac{\sqrt{4 \mid c c^{2}-1}}{2\left|c_{1}-1\right|}}\right]^{\frac{2 c-1}{2\left(c_{1}-1\right)}}, \tag{26}
\end{equation*}
$$

where $G^{ \pm}(x, \tilde{t})=G^{ \pm}\left(x, \sqrt{4|c|^{2}-1} t\right), F(x, \tilde{t})=F\left(x, \sqrt{4|c|^{2}-1} t\right), c=c_{1}+\mathrm{i} c_{2}$.

### 2.6. Single-soliton solution

For the one-soliton solution we have
$G^{ \pm}= \pm \mathrm{e}^{\eta_{1}^{ \pm}}, \quad F=1-\kappa^{2} \mathrm{e}^{\eta_{1}^{+}+\eta_{1}^{-}+\phi_{11}}, \quad \mathrm{e}^{\phi_{11}}=\frac{1}{\left(k_{1}^{+}+k_{1}^{-}\right)^{2}}$,
where $\eta_{1}^{ \pm}=k_{1}^{ \pm} x \pm\left(k_{1}^{ \pm}\right)^{2} \tilde{t}+\eta_{1}^{ \pm(0)}$, and $k_{1}^{ \pm}, \eta_{1}^{ \pm(0)}$ are arbitrary real constants. This solution is regular only if $\kappa^{2}<0$, which corresponds to the cases $p>0, c_{1}<\frac{1}{2}$ or $p<0, c_{1}>\frac{1}{2}$, when $\kappa^{2}=-1$ (see figure 1). Here, we focus on this case. From the preceding we have
$\mathrm{e}^{\hat{R}}=\sqrt{\frac{4|c|^{2}-1}{\left|p\left(2 c_{1}-1\right)\right|}} \frac{\left|k_{1}^{+}+k_{1}^{-}\right|}{2 \cosh \frac{\eta_{1}^{\eta}+\eta_{1}^{-}+\phi_{11}}{2}}, \quad \hat{S}=\frac{\sqrt{4|c|^{2}-1}}{\left|2 c_{1}-1\right|} \frac{\eta_{1}^{+}-\eta_{1}^{-}}{2}$.
Denoting $v \equiv\left(k_{1}^{-}-k_{1}^{+}\right) \sqrt{4|c|^{2}-1}, k \equiv\left(k_{1}^{-}+k_{1}^{+}\right) / 2$ and using $\tilde{t}= \pm \sqrt{4|c|^{2}-1} t$ we obtain a single-soliton solution of the model (1) in the form

$$
\begin{equation*}
u(x, t)=\sqrt{\frac{4|c|^{2}-1}{\left|p\left(2 c_{1}-1\right)\right|}} \frac{|k| \mathrm{e}^{\mathrm{i} \Phi(x, t)}}{\cosh k\left(x-v t-x_{0}\right)}, \tag{29}
\end{equation*}
$$

where
$\Phi=\frac{1}{\left|2 c_{1}-1\right|}\left[-\frac{v x}{2}+\left[\left(4|c|^{2}-1\right) k^{2}+\frac{v^{2}}{4}\right] t\right]-\frac{2 c_{2}}{2 c_{1}-1} \ln \left[\cosh k\left(x-v t-x_{0}\right)\right]+\phi_{0}$.

### 2.7. Hyperbolic metrics and black hole interpretation

Substitution of the Madelung form $u=\mathrm{e}^{R+\mathrm{i} S}$ into the Hamiltonian density (2) yields

$$
\begin{equation*}
\mathcal{H}=\left[\left(1+2 c_{1}\right) R_{x}^{2}+\left(1-2 c_{1}\right) S_{x}^{2}+4 c_{2} R_{x} S_{x}\right] \mathrm{e}^{2 R}-p \mathrm{e}^{4 R} . \tag{31}
\end{equation*}
$$

The dispersion is positive definite if $|c|<\frac{1}{2}$ and indefinite when $|c|>\frac{1}{2}$. In the present resonant case, the dispersion is of indefinite sign. Thus in terms of (5)

$$
\begin{equation*}
\mathcal{H}=\left[\left(\frac{4|c|^{2}-1}{2 c_{1}-1}\right) \hat{R}_{x}^{2}+\left(1-2 c_{1}\right) \hat{S}_{x}^{2}\right] \mathrm{e}^{2 \hat{R}}-p \mathrm{e}^{4 \hat{R}} \tag{32}
\end{equation*}
$$

whence, when $|c|>\frac{1}{2}$ the dispersion is indefinite and it changes sign at points in the spacetime where

$$
\begin{equation*}
\hat{R}_{x}= \pm \frac{1-2 c_{1}}{\sqrt{4|c|^{2}-1}} \hat{S}_{x} \tag{33}
\end{equation*}
$$

For the one-soliton solution (29) this gives

$$
\begin{equation*}
\tanh k\left(x-v t-x_{0}\right)= \pm \frac{v}{2 k} \tag{34}
\end{equation*}
$$

a solution of which exists if $|v|<2|k|$. As in [4, 5], we can construct a two-dimensional pseudo-Riemannian metric for (19), (20) and the RNLS, namely
$\mathrm{d} l^{2}=\left[\left(4|c|^{2}-1\right) \hat{R}_{x}^{2}-\left(2 c_{1}-1\right)^{2} \hat{S}_{x}^{2}\right] \mathrm{e}^{2 \hat{R}} \mathrm{~d} t^{2}-2 \hat{S}_{x}\left|2 c_{1}-1\right| \mathrm{e}^{2 \hat{R}} \mathrm{~d} x \mathrm{~d} t-\mathrm{e}^{2 \hat{R}} \mathrm{~d} x^{2}$
so that evolution according to equation (1) implies the two-dimensional spacetime with the constant scalar curvature

$$
\begin{equation*}
R=8 p \frac{2 c_{1}-1}{4|c|^{2}-1} \tag{36}
\end{equation*}
$$



Figure 2. Fusion and fission of two solitons (a) fusion of two solitons (b) fission of two solitons.

With our choice of parameters, namely $c_{1}>\frac{1}{2}, p<0$ or $c_{1}<\frac{1}{2}, p>0, R$ is negative-valued. The time component of the metric is the dispersion term $\epsilon_{0}$ for the energy

$$
\begin{equation*}
g_{00}=\left[\left(4|c|^{2}-1\right) \hat{R}_{x}^{2}-\left(2 c_{1}-1\right)^{2} \hat{S}_{x}^{2}\right] \mathrm{e}^{2 \hat{R}}=\left(2 c_{1}-1\right) \epsilon_{0} \tag{37}
\end{equation*}
$$

Points where $g_{00}$ vanishes correspond to the event horizon of a black hole. For the one-soliton solution this corresponds to condition (34). Solitons of the equation (1) moving with the velocity $|v|<2|k|$ correspond to black holes with event horizon dependent on the velocity of the soliton.

### 2.8. Two-soliton solution

The Hirota bilinear representation (22)-(24) admits two-soliton solutions with
$G^{ \pm}= \pm\left(\mathrm{e}^{\eta_{1}^{ \pm}}+\mathrm{e}^{\eta_{2}^{ \pm}}+\alpha_{1}^{ \pm} \mathrm{e}^{\eta_{1}^{ \pm}+\eta_{1}^{-}+\eta_{2}^{ \pm}}+\alpha_{2}^{ \pm} \mathrm{e}^{\eta_{2}^{+}+\eta_{2}^{-}+\eta_{1}^{ \pm}}\right)$,
$F=1+\frac{\mathrm{e}^{\eta_{1}^{+}+\eta_{1}^{-}}}{\left(k_{11}^{+-}\right)^{2}}+\frac{\mathrm{e}^{\eta_{1}^{+}+\eta_{2}^{-}}}{\left(k_{12}^{+-}\right)^{2}}+\frac{\mathrm{e}^{\eta_{2}^{+}+\eta_{1}^{-}}}{\left(k_{21}^{+-}\right)^{2}}+\frac{\mathrm{e}^{\eta_{2}^{+}+\eta_{2}^{-}}}{\left(k_{22}^{+-}\right)^{2}}+\beta \mathrm{e}^{\eta_{1}^{+}+\eta_{1}^{-}+\eta_{2}^{+}+\eta_{2}^{-}}$,
where $\eta_{i}^{ \pm}=k_{i}^{ \pm} x \pm\left(k_{i}^{ \pm}\right)^{2} \tilde{t}+\eta_{i}^{ \pm(0)}, k_{i j}^{a b}=k_{i}^{a}+k_{j}^{b},(i, j=1,2),(a, b=+-)$,
$\alpha_{1}^{ \pm}=\frac{\left(k_{1}^{ \pm}-k_{2}^{ \pm}\right)^{2}}{\left(k_{11}^{+-} k_{21}^{ \pm \mp}\right)^{2}}, \quad \alpha_{2}^{ \pm}=\frac{\left(k_{1}^{ \pm}-k_{2}^{ \pm}\right)^{2}}{\left(k_{22}^{+-} k_{12}^{ \pm \mp}\right)^{2}}, \quad \beta=\frac{\left(k_{1}^{+}-k_{2}^{+}\right)^{2}\left(k_{1}^{-}-k_{2}^{-}\right)^{2}}{\left(k_{11}^{+-} k_{12}^{+-} k_{21}^{+-} k_{22}^{+-}\right)^{2}}$.

### 2.9. Resonance interaction of solitons

In figure 2, fusion and fission of two solitons is shown for the parameter values $k_{1}^{+}=0.1$, $k_{1}^{-}=1, k_{2}^{+}=1, k_{2}^{-}=0$ and large phase shift. The horizontal and vertical axes represent space $x$ and time $t$ coordinates, respectively.


Figure 3. Two-soliton resonant state.


Figure 4. Four-soliton resonance scattering.

In figure 3, the creation of soliton resonance with a finite lifetime is shown. The parameters in this case are the same as above, except for the phase shift $d=15$.

In figure 4, four virtual soliton resonance scattering is shown for $k_{1}^{+}=2, k_{1}^{-}=1, k_{2}^{+}=1$, $k_{2}^{-}=2$ and $d=16$.

## 3. Nontrivial boundary conditions

In the application of the RNLS model to the propagation of solitonic magnetoacoustic waves in [6] the required asymptotic behavior is $|\psi|^{2}=\rho \rightarrow 1$ at infinity. In this case, we can derive a one-soliton solution of (1) with
$|u|^{2}(x, t)=1+\frac{v^{2}-4 p\left(1-2 c_{1}\right)}{4 p\left(1-2 c_{1}\right)} \operatorname{sech}^{2}\left[\frac{\sqrt{v^{2}-4 p\left(1-2 c_{1}\right)}}{2 \sqrt{4|c|^{2}-1}}\left(x+v t+x_{0}\right)\right]$
and the phase

$$
\begin{align*}
& S(x, t)=S_{0}+2 p t+\frac{c_{2}}{2 c_{1}-1} \ln |u|^{2}(x, t)  \tag{42}\\
& +\frac{\sqrt{4|c|^{2}-1}}{2\left|2 c_{1}-1\right|} \ln \frac{v+\sqrt{v^{2}-4 p\left(1-2 c_{1}\right)} \tanh \left[\frac{\sqrt{v^{2}-4 p\left(1-2 c_{1}\right)}}{2 \sqrt{4|c|^{2}-1}}\left(x+v t+x_{0}\right)\right]}{v-\sqrt{v^{2}-4 p\left(1-2 c_{1}\right)} \tanh \left[\frac{\sqrt{v^{2}-4 p\left(1-2 c_{1}\right)}}{2 \sqrt{4|c|^{2}-1}}\left(x+v t+x_{0}\right)\right]} \tag{43}
\end{align*}
$$

It is seen that the velocity of this soliton is bounded below with $|v|>2\left|p\left(1-2 c_{1}\right)\right|$. This contrasts with the case of the defocusing NLS equation where the dark soliton velocity is bounded above. Moreover if the soliton of the defocusing NLS is a hole-like (bubble) excitation with $\rho=|u|^{2}<1$, for the Malomed-Stenflo equation this has $\rho=|u|^{2}>1$. It is noted that the two-soliton solution can be constructed alternatively via a Backlund-Darboux transformation [6]. Solutions of the RNLS equation with nontrivial boundary conditions have been investigated by Lee and Pashaev in [7]. These results may be carried over 'mutatis mutandis' to the Malomed-Stenflo equation (1).

## 4. Conclusion

It has been established that the generalized nonlinear Schrödinger equation (1) introduced in [1], for a specific range of parameters, admits resonant soliton interaction. Indeed, a natural integrable extension of this equation is suggested, namely
$\mathrm{i} u_{t}+u_{x x}+2 p|u|^{2} u=\left(\bar{c} \frac{u_{x}^{2}}{u^{2}}+c \frac{\bar{u}_{x}^{2}}{\bar{u}^{2}}-2 c \frac{\bar{u}_{x x}}{\bar{u}}-2 c \frac{\bar{u}_{x} u_{x}}{\bar{u} u}\right) u+4 v \frac{|u|_{x x}}{|u|} u$
corresponding to the addition of a 'quantum potential' term with strength $\nu$. This extension can be motivated in an information theory context to reflect uncertainty conditions in the measurement process and described by the Fisher measure [8]. The generalized NLS equation (44) is Hamiltonian with

$$
\begin{equation*}
\mathcal{H}=\left|u_{x}\right|^{2}-p|u|^{4}+c \frac{u}{\bar{u}} \bar{u}_{x}^{2}+\bar{c} \frac{\bar{u}}{u} u_{x}^{2}-4 v\left(|u|_{x}\right)^{2} . \tag{45}
\end{equation*}
$$

Following the same procedure as that for (1), reduction may be made to the RNLS form (9) but now with the parameter

$$
\begin{equation*}
s=1+\frac{4|c|^{2}-1-4 \nu\left(2 c_{1}-1\right)}{\left(2 c_{1}-1\right)^{2}} . \tag{46}
\end{equation*}
$$

The reductions of the extended model equation (44) then depend on both the complex parameter $c=c_{1}+\mathrm{i} c_{2}$ and the real quantum potential strength $\nu$. In geometrical terms, the circle $|c|=\frac{1}{2}$ in figure 1 is modified by the presence of the additional parameter $v$ to become

$$
\begin{equation*}
\left(c_{1}-v\right)^{2}+c_{2}^{2}=\left(v-\frac{1}{2}\right)^{2} . \tag{47}
\end{equation*}
$$

The region inside this circle corresponds to the NLS reduction, while the outside corresponds to the resonant NLS case. It is noted that when $v=\frac{1}{2}$, the disc shrinks to a point and no reduction to the classical NLS is possible. In this case

$$
\begin{equation*}
s=1+\frac{\left(2 c_{1}-1\right)^{2}+4 c_{2}^{2}}{\left(2 c_{1}-1\right)^{2}} \tag{48}
\end{equation*}
$$

whence $s>1$ and the model equation (44) is necessarily of resonant type.

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